

# Prioritized Independent Contact Regions for Form Closure Grasps

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- Independent Contact Regions (ICR) provide robustness to grasp uncertainty
- We propose an Algorithm allowing for user-input regarding the shape of such regions
- An extension of the Grasp Wrench Space (GWS) to sets of grasps is contributed
- We introduce the concept of the Exertable Wrench Space (EWS) to evaluate grasp families

