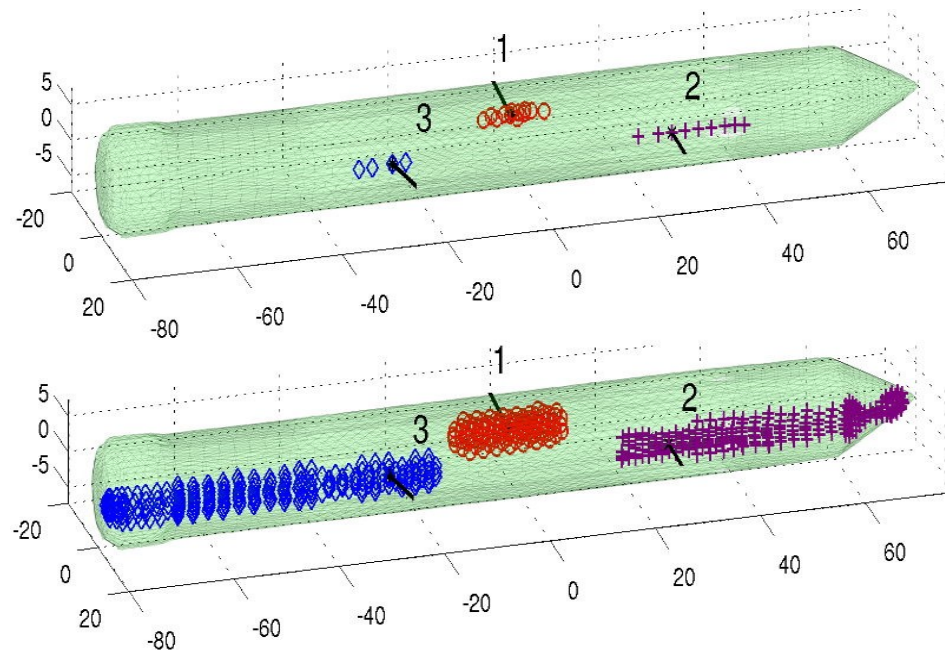


Independent Contact Regions Based on a Patch Contact Model

Krzysztof Charusta, Robert Krug, Dimitar Dimitrov, Boyko Iliev
Center of Applied Autonomous Sensor Systems (AASS),
Örebro University, Sweden

- Independent Contact Regions (ICRs) compensate for positioning inaccuracy in grasp synthesis.
- Until now ICRs have been used only with the single-point contact model.
- We extend the ICR algorithm to account for deformable fingers with large contact areas.



ICRs: before (up), and after (down)
our solution was used.