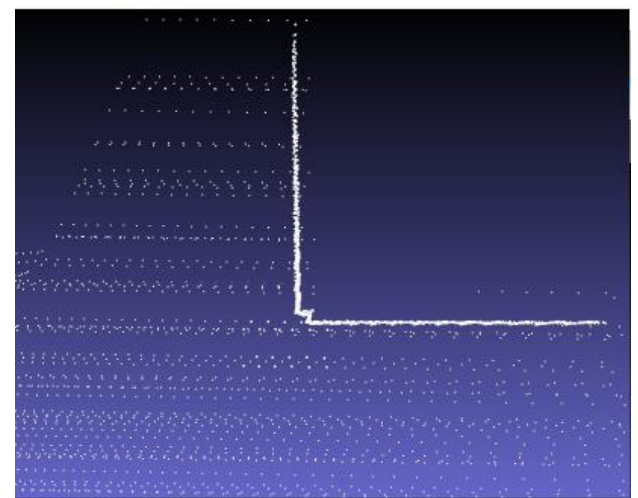
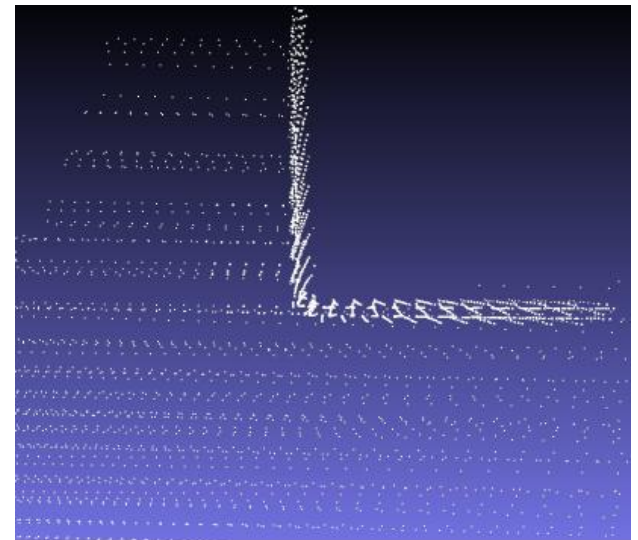


Improving Point-Cloud Accuracy from a Moving Platform

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- We present a method for improving the accuracy of 3D point clouds made while moving over rough terrain.
- No requirements on particular features of the environment, or inertial sensors.
- Perform local, per-scan, pose-graph SLAM using NDT to form the constraints of the graph.



Point cloud before (above)
and after (below) improvement.